

## 6. MAC 093

### 6.1. Technical Data

Designation	Symbol	Unit	Motor type MAC ...		
			093 A - - - WS	093 B - - - OS	093 C - - - KS
Nominal motor speed <sup>1)</sup>	n	min <sup>-1</sup>	2000	2000	2000
Continuous torque at standstill <sup>2)</sup>	M <sub>dN</sub>	Nm	9.2 (12.0) <sup>5)</sup>	14.5 (20.0) <sup>5)</sup>	19.5 (28.0) <sup>5)</sup>
Continuous current at standstill	I <sub>dN</sub>	A	11(14) <sup>5)</sup>	18 (25) <sup>5)</sup>	22 (32) <sup>5)</sup>
Rotor moment of inertia <sup>3)</sup>	J <sub>M</sub>	kgm <sup>2</sup>	22 x 10 <sup>-4</sup>	29 x 10 <sup>-4</sup>	42 x 10 <sup>-4</sup>
Torque constant at 20 °C	K <sub>m</sub>	Nm/A	0.875	0.831	0.910
Windings resistance at 20 °C	R <sub>A</sub>	Ohm	1.313	0.625	0.433
Windings inductance	L <sub>A</sub>	mH	16.0	9.0	7.0
Maximum peak of pulse current	I <sub>peak</sub>	A	54	89	110
Thermal time constant	T <sub>th</sub>	min	50 (30) <sup>5)</sup>	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>
Mass <sup>4)</sup>	m <sub>M</sub>	kg	13.0	16.5	22.0
			093 A - - - PS	093 B - - - JS	093 C - - - FS
Nominal motor speed <sup>1)</sup>	n	min <sup>-1</sup>	3000	3000	3000
Continuous torque at standstill <sup>2)</sup>	M <sub>dN</sub>	Nm	9.2 (12.0) <sup>5)</sup>	14.5 (18.3) <sup>5)</sup>	19.5 (28.0) <sup>5)</sup>
Continuous current at standstill	I <sub>dN</sub>	A	15 (20) <sup>5)</sup>	27 (34) <sup>5)</sup>	35 (50) <sup>5)</sup>
Rotor moment of inertia <sup>3)</sup>	J <sub>M</sub>	kgm <sup>2</sup>	22 x 10 <sup>-4</sup>	29 x 10 <sup>-4</sup>	42 x 10 <sup>-4</sup>
Torque constant at 20 °C	K <sub>m</sub>	Nm/A	0.620	0.554	0.579
Windings resistance at 20 °C	R <sub>A</sub>	Ohm	0.659	0.227	0.175
Windings inductance	L <sub>A</sub>	mH	8.0	4.0	2.9
Maximum peak of pulse current	I <sub>peak</sub>	A	76	134	173
Thermal time constant	T <sub>th</sub>	min	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>
Mass <sup>4)</sup>	m <sub>M</sub>	kg	13.0	16.5	22.0
			093 A - - - LS	093 B - - - GS	093 C - - - DS
Nominal motor speed <sup>1)</sup>	n	min <sup>-1</sup>	4000	4000	4000
Continuous torque at standstill <sup>2)</sup>	M <sub>dN</sub>	Nm	9.2 (12.0) <sup>5)</sup>	14.5 (20.0) <sup>5)</sup>	19.5 (28.0) <sup>5)</sup>
Continuous current at standstill	I <sub>dN</sub>	A	22 (28) <sup>5)</sup>	38 (53) <sup>5)</sup>	48 (69) <sup>5)</sup>
Rotor moment of inertia <sup>3)</sup>	J <sub>M</sub>	kgm <sup>2</sup>	22 x 10 <sup>-4</sup>	29 x 10 <sup>-4</sup>	42 x 10 <sup>-4</sup>
Torque constant at 20 °C	K <sub>m</sub>	Nm/A	0.438	0.388	0.413
Windings resistance at 20 °C	R <sub>A</sub>	Ohm	0.328	0.136	0.089
Windings inductance	L <sub>A</sub>	mH	4.0	2.0	1.5
Maximum peak of pulse current	I <sub>peak</sub>	A	108	192	242
Thermal time constant	T <sub>th</sub>	min	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>
Mass <sup>4)</sup>	m <sub>M</sub>	kg	13.0	16.5	22.0
			093 A - - - HS	093 B - - - ES	093 C - - - CS
Nominal motor speed <sup>1)</sup>	n	min <sup>-1</sup>	6000	6000	6000
Continuous torque at standstill <sup>2)</sup>	M <sub>dN</sub>	Nm	9.2 (9.8) <sup>5)</sup>	14.5 (20.0) <sup>5)</sup>	19.5 (28.0) <sup>5)</sup>
Continuous current at standstill	I <sub>dN</sub>	A	32 (34) <sup>5)</sup>	54 (74) <sup>5)</sup>	60 (87) <sup>5)</sup>
Rotor moment of inertia <sup>3)</sup>	J <sub>M</sub>	kgm <sup>2</sup>	22 x 10 <sup>-4</sup>	29 x 10 <sup>-4</sup>	42 x 10 <sup>-4</sup>
Torque constant at 20 °C	K <sub>m</sub>	Nm/A	0.292	0.277	0.331
Windings resistance at 20 °C	R <sub>A</sub>	Ohm	0.146	0.069	0.057
Windings inductance	L <sub>A</sub>	mH	1.8	1.0	0.9
Maximum peak of pulse current	I <sub>peak</sub>	A	162	268	302
Thermal time constant	T <sub>th</sub>	min	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>	50 (45) <sup>5)</sup>
Mass <sup>4)</sup>	m <sub>M</sub>	kg	13.0	16.5	22.0

<sup>1)</sup> The usable motor speed is determined by the drive used.  
 Only those usable speeds n<sub>max</sub> found in the selection lists of the motor-drive combinations are binding.  
<sup>2)</sup> With 60K overtemperature at the motor housing.  
 Continuous torque can be limited by the drive. See selection data.  
<sup>3)</sup> With tachogenerator, without holding brake  
<sup>4)</sup> With tachogenerator, without holding brake, without blower.  
<sup>5)</sup> Parenthetical values apply to versions with surface cooling.

Fig 6.1: Type-dependent motor data

Designation	Symbol	Unit	Data	
Permissible ambient temperature	$T_{um}$	°C	0 ... + 45	
Permissible storage and transport temperature	$T_L$	°C	-20 ... +80	
Maximum installation elevation		m	1000 m. above sea level	
Protection category			IP 65	
Insulation classification			F	
Housing coat			Black prime coat (RAL 9005)	
Voltage constant of the tachogenerator <sup>1)</sup>	$C_w$	Vs/rad V/min <sup>-1</sup>	0.0143 1.5/1000	0.0286 3/1000

<sup>1)</sup> Tachovoltage can be selected application-related.

Fig 6.2: General data MAC 093

Designation	Symbol	Unit	Data holding brake		
			Standard	heavy-duty electrically actuated release	extra heavy-duty
Principle of action					
Holding torque	$M_H$	Nm	6.5	14	22
Nominal voltage	$U_N$	V		DC 24 ± 10%	
Nominal current	$I_N$	A	0.7	0.7	0.7
Moment of inertia	$J_B$	kgm <sup>2</sup>	1.06 x 10 <sup>-4</sup>	3.6 x 10 <sup>-4</sup>	3.6 x 10 <sup>-4</sup>
Release delay	$t_L$	ms	60	70	70
Clamping delay	$t_K$	ms	20	30	30
Mass	$m_B$	kg	0.6	1.1	1.1

Fig 6.3: Technical data - holding brake

Designation	Symbol	Unit	Axial cooling	Radial cooling
Power consumption	$S_N$	VA	40/42	40/42
Nominal voltage	$U_N$	V	AC 230 or 115 <sup>1)</sup>	AC 230 or 115 <sup>1)</sup>
Frequency	f	Hz	50/60	50/60
Mass	$m_L$	kg	approx. 3.3 <sup>2)</sup>	approx. 3.2 <sup>2)</sup>
Protection category blower unit			IP 24	IP 24
Protection category blower motor			IP 44	IP 44

<sup>1)</sup> 115 V special design  
<sup>2)</sup> Blower shroud for motor with tachofeedback

Fig 6.4: Technical data - surface cooling

### 6.4. Dimensional data - natural convection

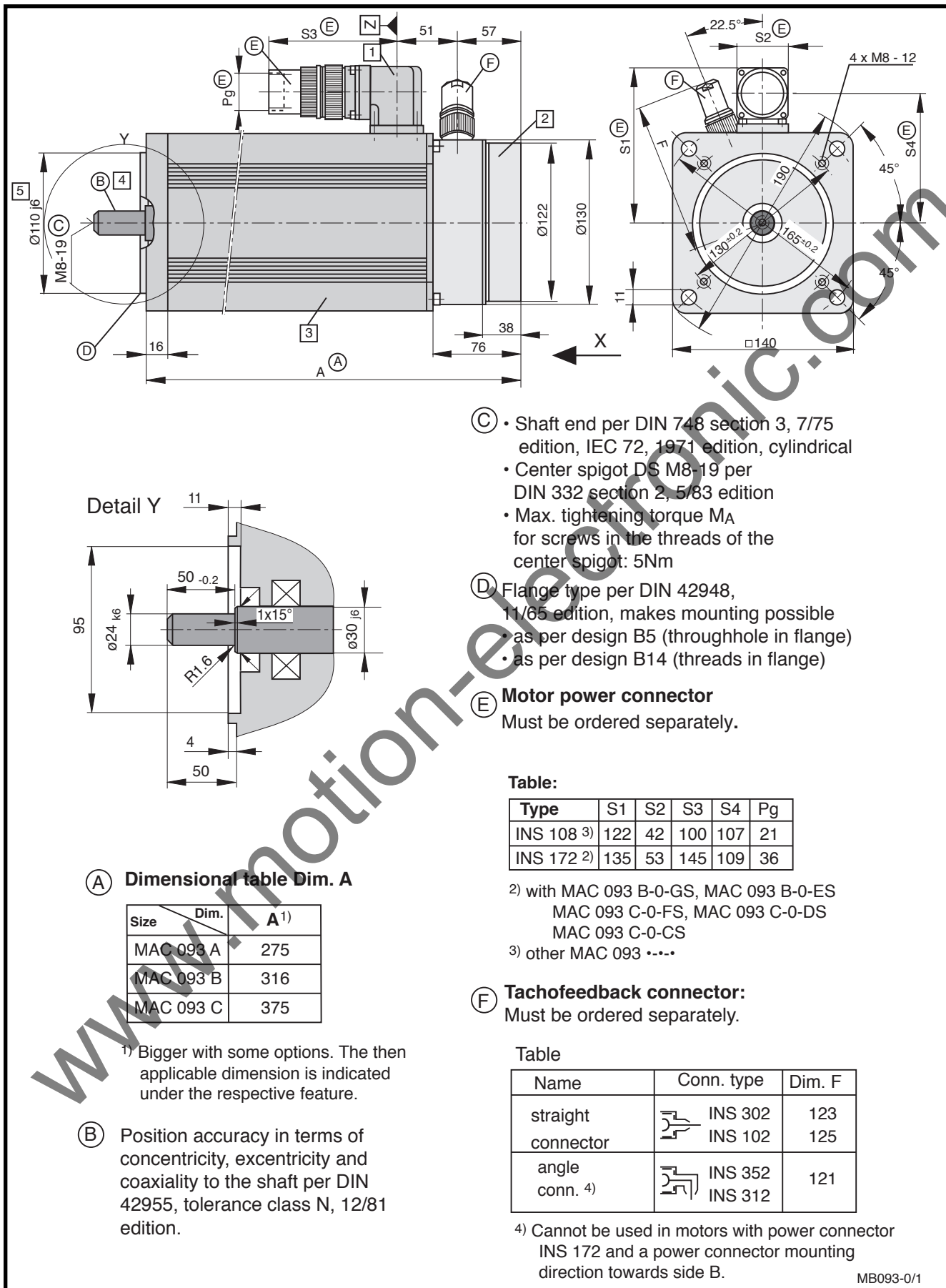


Fig 6.13: Dimensional data - MAC 093 (natural convection)

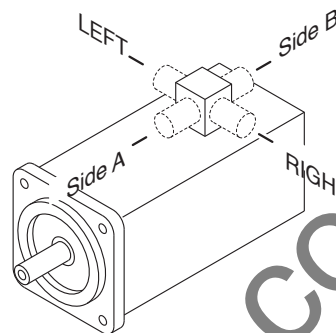
**Available options**

**1 Power connection**

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

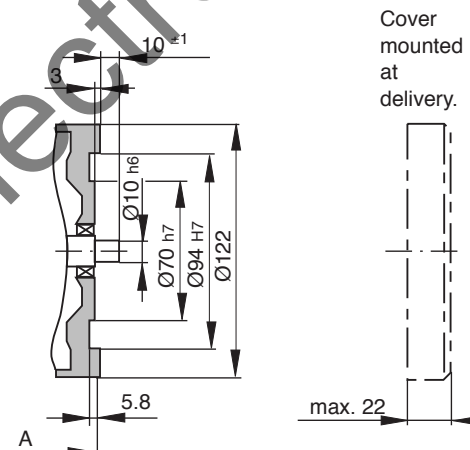
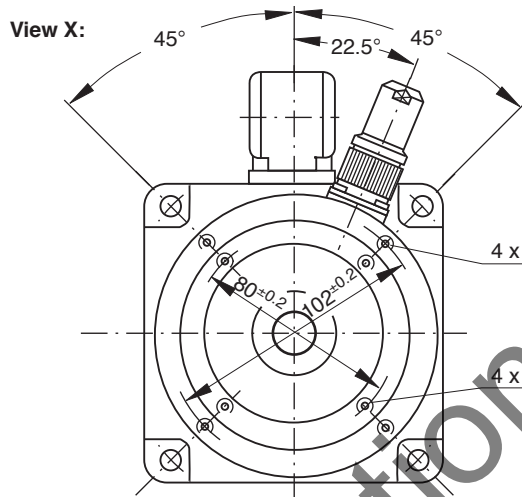
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.

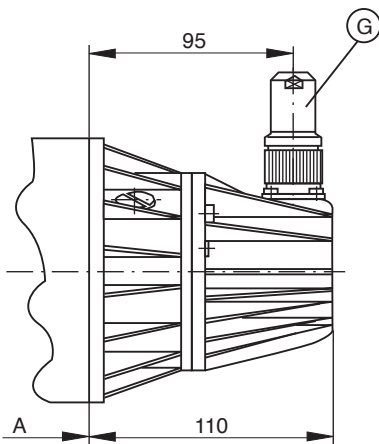
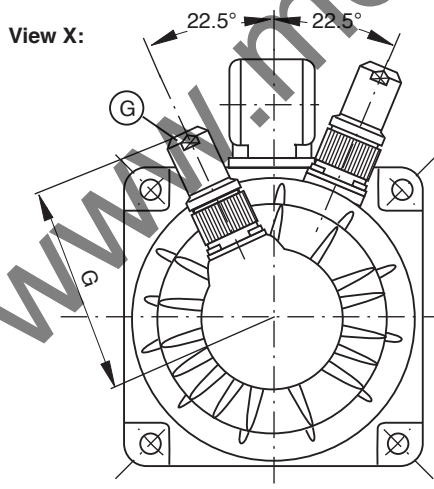


**2 Motor version**

- Tachofeedback and second shaft end



- Tachofeedback and mounted incremental encoder



**G Incremental encoder connector**

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	88
	INS 101	90
angle conn.	INS 351	86
	INS 311	

- Tachofeedback and mounted absolute encoder (see following page)

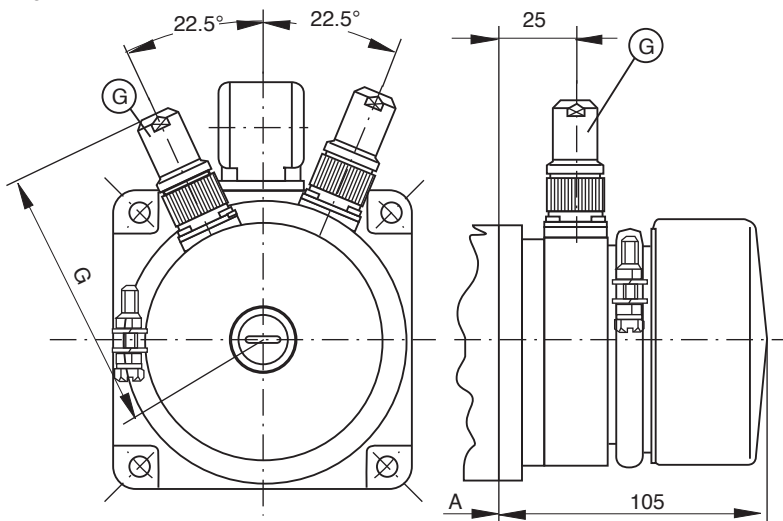
MB093-0/2

Fig 6.14: Dimensional data - MAC 093 - available options - (natural convection)

### Available options

- Tachofeedback and mounted absolute encoder

View X:



**G Absolute encoder conn.**  
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106
angle conn.	INS 322	102

#### 3 Blocking brake

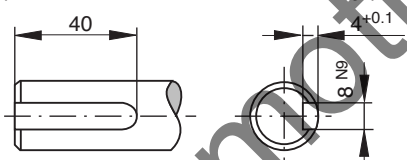
- without blocking brake  
Dim. A retained
- Standard blocking brake: 6.5 Nm  
Dim. A. retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

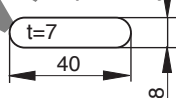
Size	Dim.	
	A	
MAC 093 A	305	
MAC 093 B	346	
MAC 093 C	405	

#### 4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition  
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40  
Must be ordered separately



#### 5 Special centering diameter

- Ø130 j6

MB093-0/3

Fig 6.15: Dimensional data - MAC 093 - available options - (natural convection)

### 6.5. Dimensional data - radial cooling

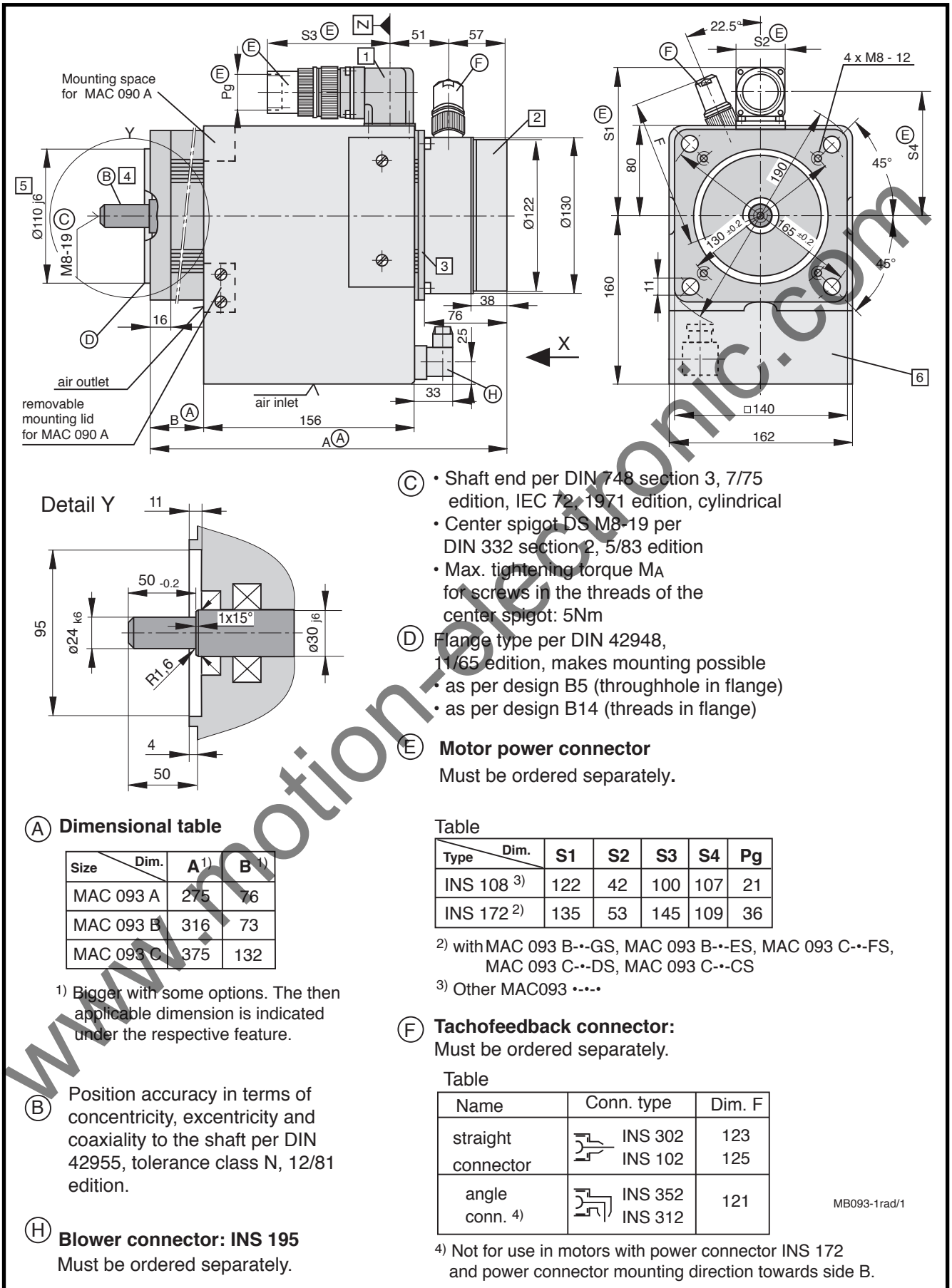


Fig 6.16: Dimensional data - MAC 093 (radial cooling)

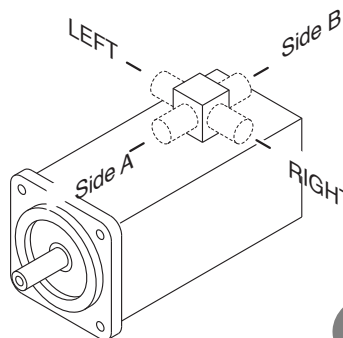
### Available options

**1 Power connection**

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

- to side A
- to side B
- to the right
- to the left

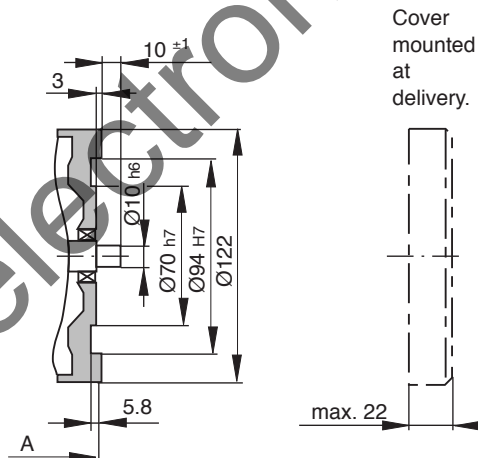
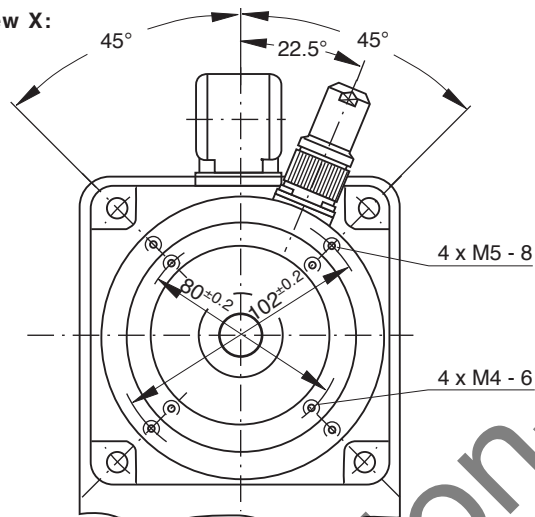
The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



**2 Motor version**

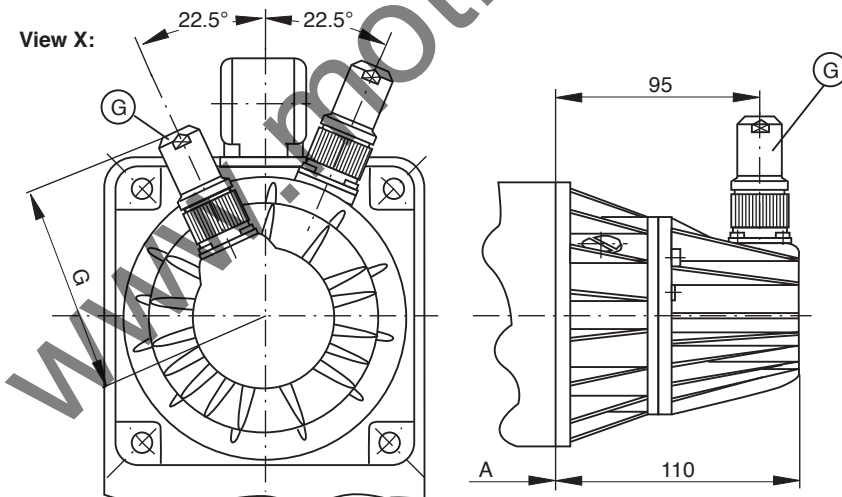
- Tachofeedback and second shaft end

View X:



- Tachofeedback and mounted incremental encoder

View X:



**G Incremental encoder connector**

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	88
	INS 101	90
angle conn.	INS 351 INS 311	86

- Tachofeedback and mounted absolute encoder (see following page)

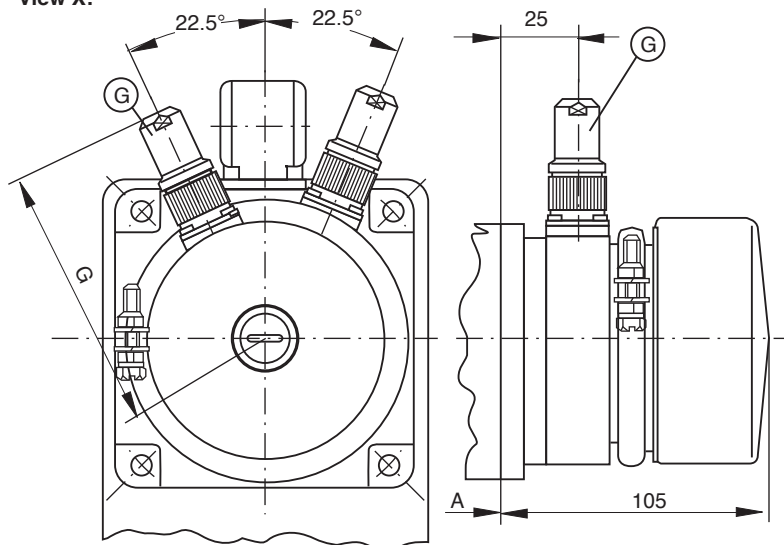
MB090-1rad/2

Fig 6.17: Dimensional data - MAC 093 - available options - (radial cooling)

### Available options

- Tachofeedback and mounted absolute encoder

View X:



**G Absolute encoder conn.**  
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326	104
	INS 92	106
angle conn.	INS 322	102

#### 3 Blocking brake

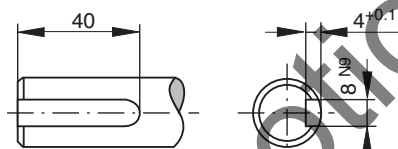
- without blocking brake  
Dim. A and B retained
- Standard blocking brake: 6.5 Nm  
Dim. A and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

Table for blocking brake with 14 and 22 Nm

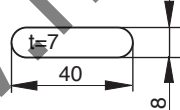
Size	Dim.	A	B
MAC 093 A		305	106
MAC 093 B		346	103
MAC 093 C		405	162

#### 4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition  
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 40  
Must be ordered separately.

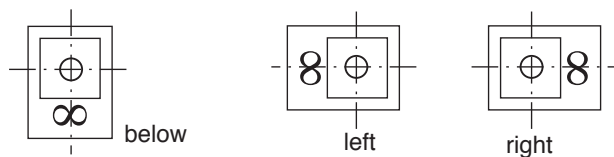


#### 5 Special centering diameter

- $\varnothing 130 j6$

#### 6 Blower arrangement

Looking towards motor shaft.



MB093-1rad/3

Fig 6.18: Dimensional data - MAC 093 - available options - (radial cooling)



### 6.6. Dimensional Data - Axial Cooling

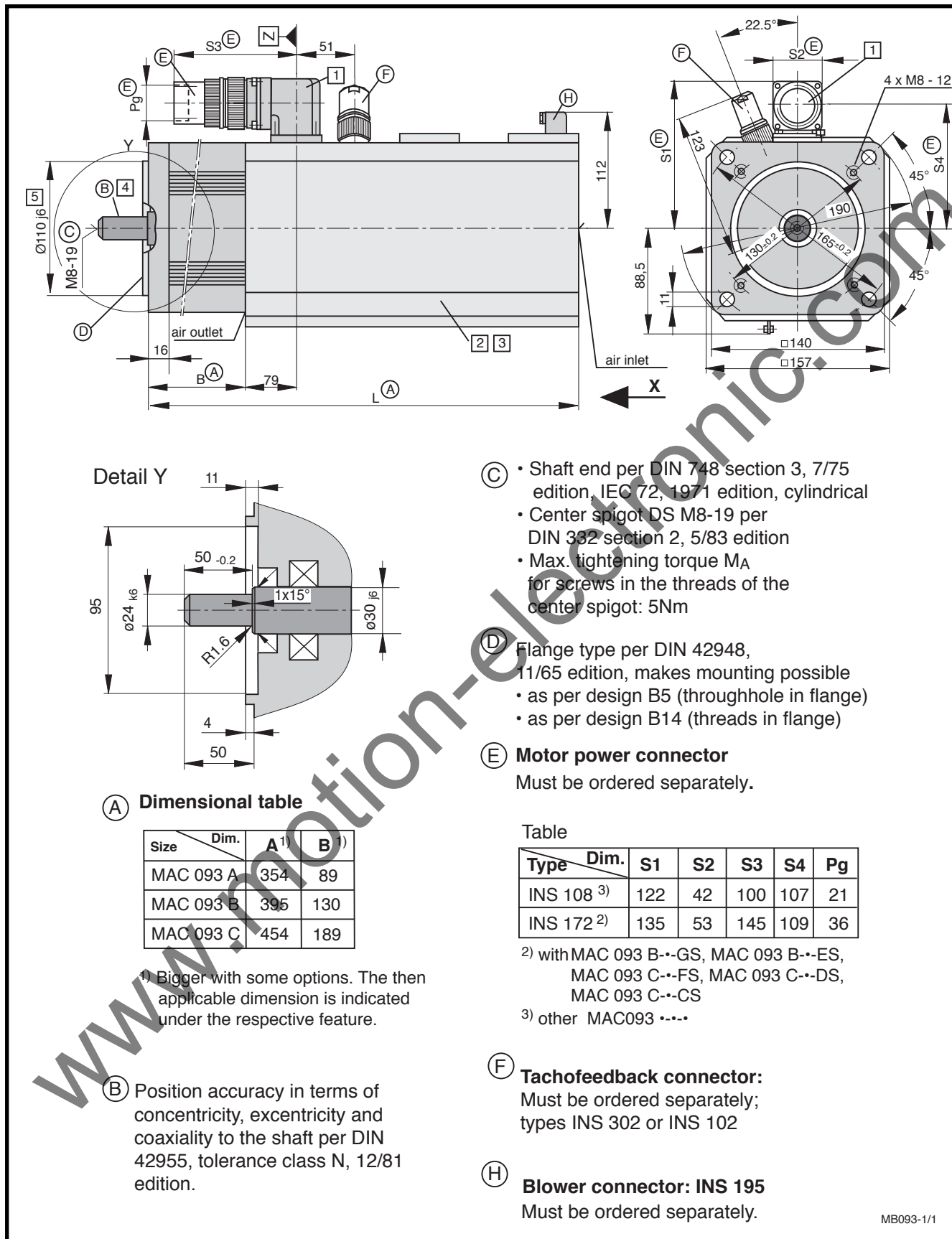


Fig 6.19: Dimensional data - MAC 093 (axial cooling)

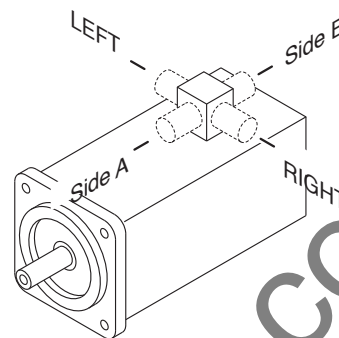
### Available options

**1 Power connection**

The output direction of the electrical power connector is selected at the time the order is placed. Possible output directions are:

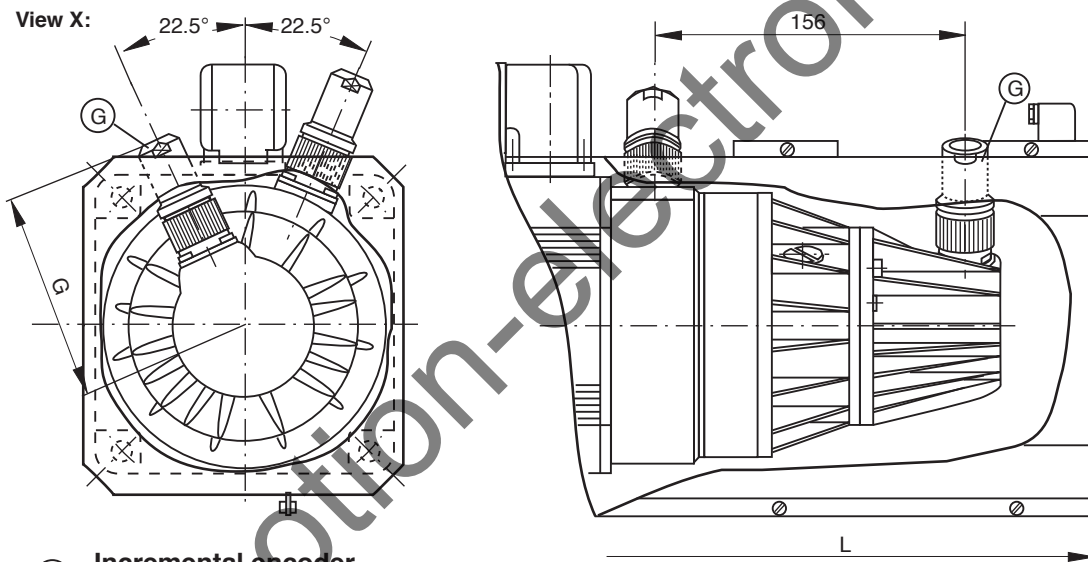
- to side A
- to side B
- to the right
- to the left

The drawing depicts side A as output direction. The dimensions of any other direction are obtained by a virtual turning of the connector housing around the Z axis.



**2 Motor version**

- Tachofeedback and mounted incremental encoder



**G Incremental encoder connector**

Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 301	123
	INS 101	125

Table:

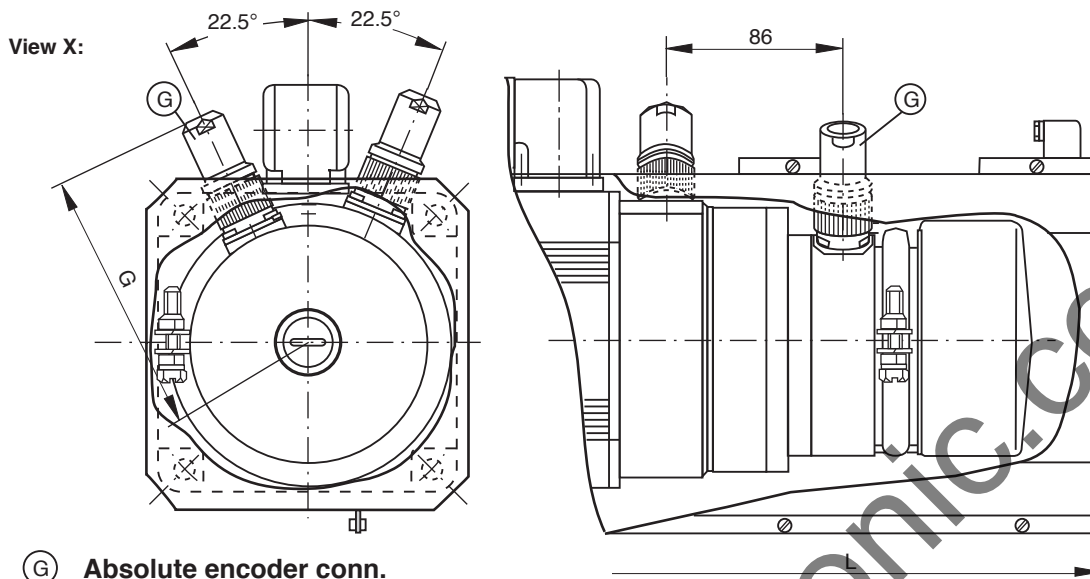
Size	Dim.	L	B
MAC 093 A		454	89
MAC 093 B		495	130
MAC 093 C		554	189

MB093-1/2


Fig 6.20: Dimensional data - MAC 093 - available options - (axial cooling)

### Available options

- Tachofeedback and mounted absolute encoder



**G Absolute encoder conn.**  
Must be ordered separately.

Name	Conn. type	Dim. G
straight conn.	INS 326 	104
	INS 92	106

Size	Dim.	L	B
MAC 093 A		454	89
MAC 093 B		495	130
MAC 093 C		554	189

#### 3 Blocking brake

- without blocking brake  
Dim. L and B retained
- Standard blocking brake: 6.5 Nm  
Dim. L and B retained
- heavy-duty blocking brake: 14.0 Nm
- extra heavy-duty blocking brake: 22.0 Nm

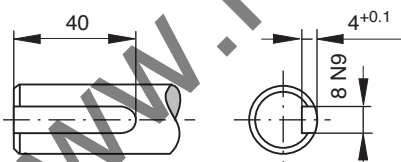
**Table for blocking brake with 14 and 20 Nm**

Size	Dim.		Vers. 4	
	L	B	L	B
MAC 093 A	384	119	484	119
MAC 093 B	425	160	525	160
MAC 093 C	484	219	584	219

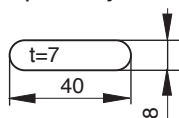
Vers. 2 = Motor with tachofeedback  
Vers. 4 = Motor with tachofeedback and mounted encoder

#### 4 Output shaft

- plain shaft (recommended type)
- with keyway per DIN 6885 sh. 1, 8/68 edition  
(Note! balanced with entire key.)



Matching key: DIN 6885-A 8 x 7 x 50  
Must be ordered separately.



#### 5 Special centering diameter

- Ø130 j6

MB093-1/3

Fig 6.21: Dimensional data - MAC 093 - available options - (axial cooling)

### 6.7. Available Options

Type code fields		Example:	MAC 093 A-0-LS-4 - C/110-A-0/WI 520LV/S000							
1. Motor for analogue drives		MAC								
2. Motor size		093								
3. Motor length		A, B, C								
4. Type of cooling:										
natural convection			surface cooling							
			axial				radial			
					blower right		blower below		blower left	
			AC	AC	AC	AC	AC	AC	AC	AC
			230 V	115 V	230 V	115 V	230 V	115 V	230 V	115 V
0			1 <sup>1)</sup>	2 <sup>1)</sup>	6	A	7	B	8	C
5. Type of windings			Motor length							
Nominal rpm			A		B		C			
2000 min <sup>-1</sup>			WS		OS		KS			
3000 min <sup>-1</sup>			PS		JS		FS			
4000 min <sup>-1</sup>			LS		GS		DS			
6000 min <sup>-1</sup>			HS		ES		CS			
6. Motor feedback										
Motor type										
with tachofeedback		2								
with tachofeedback and second shaft end		3								
with tachofeedback and mounted incremental or absolute encoder		4								
Tacho voltage										
set to nominal motor speed		-								
(nominal rpm > 3000 min <sup>-1</sup> )		: 1.5 V/1000 min <sup>-1</sup>								
(nominal rpm ≤ 3000 min <sup>-1</sup> )		: 3 V/1000 min <sup>-1</sup>								
1.5 V/1000 min <sup>-1</sup>		H								
Tacho type										
Standard		C								
increased smooth run quality		F								
7. Centering diameter										
for design B05 and B14		110								
for design B05 and B14		130								
8. Power connection										
connector to side A		A								
connector to side B		B								
connector to right (looking onto output shaft)		R								
connector to left (looking onto output shaft)		L								
9. Blocking brake										
without blocking brake		0								
with standard blocking brake (6.5 Nm)		1								
with heavy-duty blocking brake (14 Nm)		2								
with extra heavy-duty blocking brake (22 Nm)		3								
10. Type										
Incremental encoder with standard mounting		WI								
Incremental encoder with shock-damped mounting		DI								
Absolute encoder		AM								
11. Encoder code										
For available types, see section 2.4 "Motor feedback"										
12. Special types										
Fixed and documented by INDRAMAT with special number (see Drawing no.: 106-0105-4301-XX)										
Does not apply to standard motors.										

1) For type 3 motors (with 2nd shaft end and tachofeedback).  
Not available with axial surface cooling.  
2) Type code fields 10 and 11 do not apply to motor types 2 and 3.

TLMAC093

Fig 6.22: Type codes - MAC 093

## 6.8. Special Options

Specification of Option	S005
with keyway per DIN 6885, sheet 1	X

Fig 6.23: Special options with a MAC 093

www.motion-electronic.com